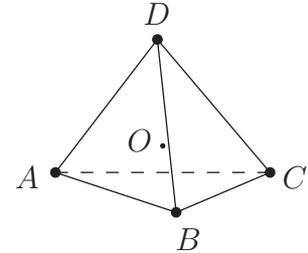


Exercises to Group Theory for Physicists — Sheet 5

Prof. S. Dittmaier and Dr. P. Maierhöfer, Universität Freiburg, SS19

Exercise 5.1 *Tetrahedral symmetry group T* (5 points)

The tetrahedral symmetry group T is the group of all rotational symmetries of a tetrahedron (i.e. without reflexions), comprising 12 elements: the identity e , two rotations (with angles 120° and 240°) around each of the four axes OA , OB , OC , OD , and three rotations (with angle 180°) around the three axes linking opposite edges (e.g. AD and BC).



- a) The tetrahedral group can be defined by the presentation $\langle a, b \mid a^2 = b^3 = (ab)^3 = e \rangle$. Show that

$$a = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \quad \text{and} \quad b = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

generate a 3-dimensional representation of the group. Is this representation irreducible or reducible? (Prove your answer!)

- b) What are the dimensions of all inequivalent irreducible representations of T ?
- c) What are the classes of T ?
- d) Determine the character table of T .
- e) Which statement can be made on the possible degrees of degeneracy of energy eigenstates of an electron in a molecule that has T as its symmetry group?

Exercise 5.2 *Rotation matrices* (2 points)

Consider a rotation about the vector $\vec{\theta} = \theta \vec{e}$ in 3-dimensional space, i.e. about an axis \vec{e} ($\vec{e}^2 = 1$) with an angle θ ($0 \leq \theta \leq \pi$).

- a) Show that the 3×3 matrix $R(\vec{\theta})$ for this rotation is given by

$$R(\vec{\theta}) = \cos \theta \mathbb{1} + (1 - \cos \theta) \vec{e} \vec{e}^T + \sin \theta \vec{e} \cdot (-i\vec{I}), \quad (1)$$

upon directly evaluating the exponential series $R(\vec{\theta}) = \exp\{-i\vec{\theta} \cdot \vec{I}\}$ with $(I_a)_{bc} = -i\epsilon_{abc}$.

- b) Derive formulas that deliver θ and the components of \vec{e} directly from the components of the matrix $R(\vec{\theta})$. Use these results to determine θ and \vec{e} for the rotation

$$R(\vec{\theta}) = \frac{1}{3} \begin{pmatrix} 2 & 2 & -1 \\ -1 & 2 & 2 \\ 2 & -1 & 2 \end{pmatrix}. \quad (2)$$

Please turn over!

Exercise 5.3 *Euler's ϕ -function and the modular inverse* (2 points)

Let G_p , $p \in \mathbb{N}$, $p > 1$, be the set of integers $1 \leq k < p$ which are co-prime to p (i.e. the only common factor of k and p is 1). The multiplication modulo p , denoted by \circ , is obviously associative and has the neutral element 1.

a) Show that G_p is closed w.r.t. \circ , i.e. that $a \circ b \in G_p \forall a, b \in G_p$.

Hint: ab and p are co-prime by assumption. Use a proof by contradiction.

b) For k, p co-prime it is guaranteed that the equation $xk + yp = 1$ has a solution for $x, y \in \mathbb{Z}$, i.e. the modular inverse $x = k^{-1} \pmod{p}$ exists. Show that $k^{\phi(p)} = 1 \pmod{p} \forall k \in G_p$ (Euler's theorem), where $\phi(p) = |G_p|$ is Euler's ϕ -function. Use this to find the inverse of k . What is $\phi(p)$ in the case that p is prime?

Remarks:

- The modular inverse can also be calculated by the extended Euclidean algorithm.
- For p prime, the set $\mathbb{F}_p = \{0, 1, \dots, p-1\}$ is a field w.r.t. addition $+$ and multiplication \circ both modulo p , i.e. $(\mathbb{F}_p, +)$ is an abelian group with neutral element 0, $(\mathbb{F}_p \setminus \{0\}, \circ)$ is an abelian group, and distributive laws hold. The so-called *modular arithmetic* on \mathbb{F}_p is of fundamental importance in modern computer algebra.