

Exercise 5.1 *Time-reversal operator* (3 points)

The time-reversal operator \mathcal{T} is antilinear (!) and defined by the following action on position eigenstates:

$$\mathcal{T}|\vec{x}\rangle = |\vec{x}\rangle. \quad (1)$$

Additionally \mathcal{T} inverts the sign of the external time dependence in potentials $V(\vec{x}, t)$, i.e. $\mathcal{T}V(\vec{x}, t)\mathcal{T}^{-1} = V(\vec{x}, -t)$. Recall the basic properties of antilinear and antiunitary operators, as e.g. given in Exercise 2.2. (Spin will not be considered in this exercise.)

- a) Show that \mathcal{T} is antiunitary and acts on position-space wave functions as $\mathcal{T}\psi(\vec{x}, t) = \psi(\vec{x}, t)^*$. Derive the operators $\hat{x}', \hat{p}', \hat{L}'$, where $A' = \mathcal{T}A\mathcal{T}^{-1}$ is the time-reversed version of an operator A . Here $\hat{L} = \vec{x} \times \hat{p}$ is the usual orbital angular momentum of a single particle.
- b) Show that $\mathcal{T}\psi(\vec{x}, t) = \psi(\vec{x}, -t)$ for states obeying $\mathcal{T}|\psi(t=0)\rangle = |\psi(0)\rangle$ upon deriving the relation $\mathcal{T}U(t, 0)\mathcal{T}^{-1} = U(-t, 0)$ for the time evolution operator $U(t, t_0)$ of a system with a time-dependent Hamiltonian $\hat{H}(t)$ whose external time dependence is symmetric under time reversal, i.e. $\hat{H}(-t) = \hat{H}(t)$.
- c) Derive the time-reversed operators of the electromagnetic potentials and field strengths $\vec{A}'(\vec{x}, t)$, $\Phi'(\vec{x}, t)$, $\vec{E}'(\vec{x}, t)$, $\vec{B}'(\vec{x}, t)$, upon analyzing Maxwell's equations and the fact that electric charges do not change sign under time reversal.

Exercise 5.2 *Rotation matrices* (2 points + 1 bonus point)

Consider a rotation about the vector $\vec{\theta} = \theta\vec{e}$ in 3-dimensional space, i.e. about an axis \vec{e} ($\vec{e}^2 = 1$) with an angle θ ($0 \leq \theta \leq \pi$).

- a) Show that the 3×3 matrix $R(\vec{\theta})$ for this rotation is given by

$$R(\vec{\theta}) = \cos\theta \mathbf{1} + (1 - \cos\theta) \vec{e}\vec{e}^T + \sin\theta \vec{e} \times, \quad (2)$$

upon directly evaluating the exponential series $R(\vec{\theta}) = \exp\{\vec{\theta} \cdot \vec{I}\}$ with $(I_a)_{bc} = -\epsilon_{abc}$.

- b) Derive (short!) formulas that deliver θ and the components of \vec{e} directly from the components of the matrix $R(\vec{\theta})$. Use these results to determine θ and \vec{e} for the rotation

$$R(\vec{\theta}) = \frac{1}{3} \begin{pmatrix} 2 & -1 & 2 \\ 2 & 2 & -1 \\ -1 & 2 & 2 \end{pmatrix}. \quad (3)$$

- c) Earn a bonus point for deriving θ and \vec{e} for a general rotation $R(\alpha, \beta, \gamma)$ that is parametrized by the Euler angles α, β, γ as defined in the lecture.

Please turn over!

Exercise 5.3 *Angular momentum eigenstates reloaded* (2 points)

Consider the operators J_a ($a = 1, 2, 3$) of angular momentum, which obey the commutation relations

$$[J_a, J_b] = i\hbar \sum_c \epsilon_{abc} J_c, \quad (4)$$

and the related operators $\vec{J}^2 = \sum_a J_a J_a$ and $J_{\pm} = J_1 \pm iJ_2$.

- a) Derive all commutators of J_3 , J_{\pm} , and \vec{J}^2 .
- b) Derive all allowed values of the parameters j and m which parametrize the eigenstates $|j, m\rangle$ of \vec{J}^2 and J_3 as follows,

$$\vec{J}^2 |j, m\rangle = \hbar^2 j(j+1) |j, m\rangle, \quad J_3 |j, m\rangle = \hbar m |j, m\rangle. \quad (5)$$

- c) Derive the relations

$$J_{\pm} |j, m\rangle = c_{jm}^{\pm} |j, m \pm 1\rangle \quad (6)$$

and explicitly determine the constants c_{jm}^{\pm} .

- d) Write down the explicit form of the matrices representing J_3 , J_{\pm} , and \vec{J}^2 for the three smallest values of j .